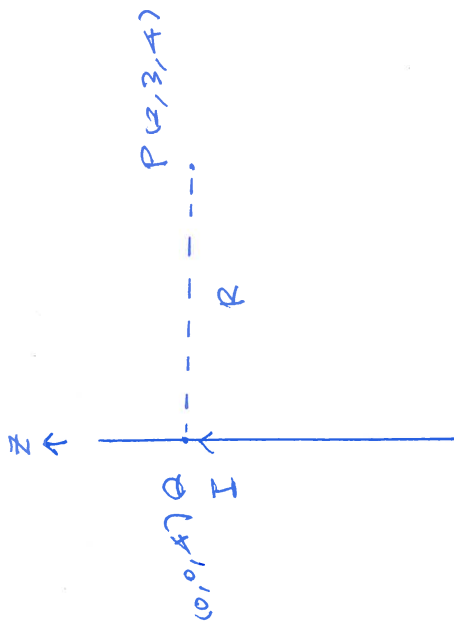


전자기학 7장 연습문제

7.1

(a)



$$I = 8 \times 10^{-3} \text{ (A)}$$

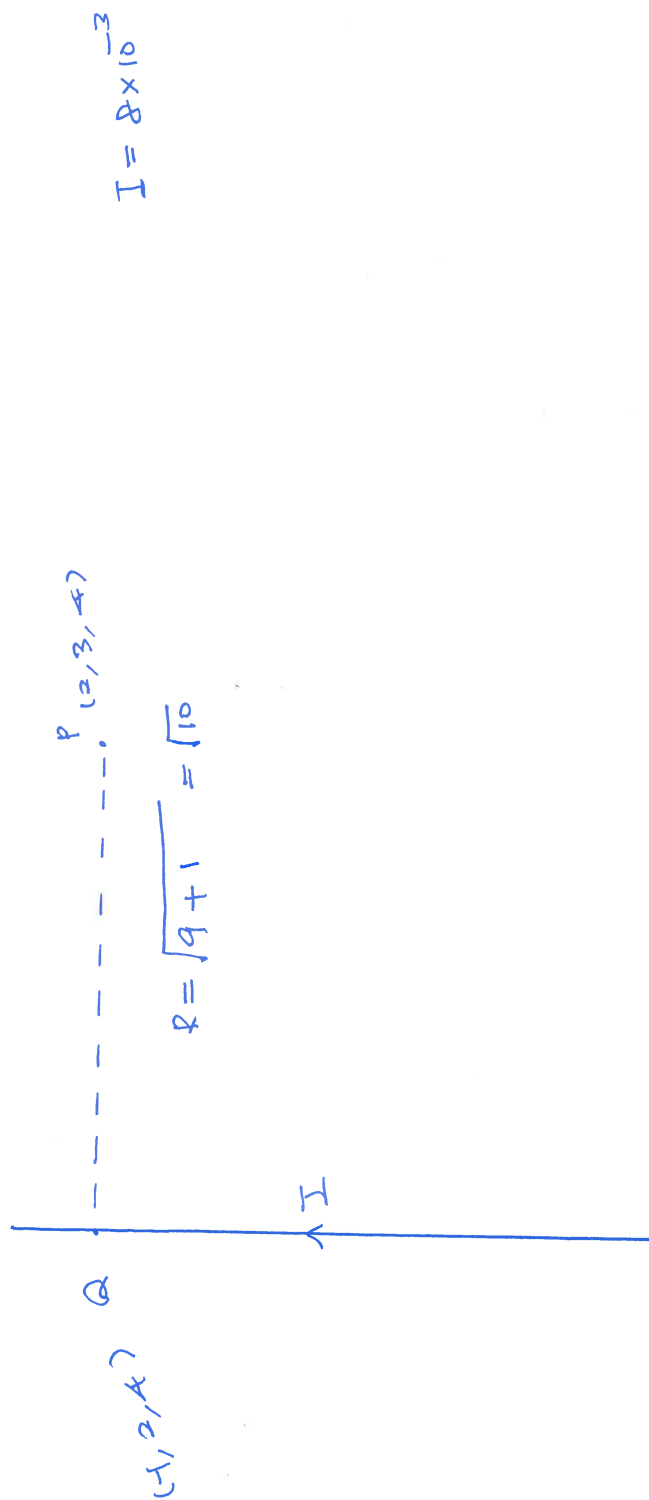
$$R = \sqrt{3^2 + 4^2} = \sqrt{13}$$

$$\vec{H} = \frac{I}{2\pi R} \hat{\phi} \quad - \textcircled{1}$$

$$\hat{\phi} = \hat{z} \times \frac{\vec{QP}}{R} = \frac{1}{\sqrt{13}} \hat{z} \times (2\hat{x} + 3\hat{y}) = \frac{1}{\sqrt{13}} (2\hat{y} - 3\hat{x}) \quad - \textcircled{2}$$

$$\begin{aligned} \vec{H} &= \frac{8 \times 10^{-3}}{2\pi \sqrt{13}} \frac{1}{\sqrt{13}} (2\hat{y} - 3\hat{x}) = -0.294 \times 10^{-3} \hat{x} + 0.196 \times 10^{-3} \hat{y} \text{ (A/m)} \\ &= -294 \hat{x} + 196 \hat{y} \text{ (}\mu\text{A/m)} \end{aligned}$$

(b)



$$R = \sqrt{9+1} = \sqrt{10}$$

$$\vec{H} = \frac{I}{2\pi R} \hat{\phi} \quad - \textcircled{1}$$

$$\hat{\phi} = \hat{z} \times \frac{\vec{QP}}{R} = \frac{1}{R} \hat{z} \times (3\hat{x} + \hat{y}) = \frac{1}{R} (3\hat{y} - \hat{x}) \quad - \textcircled{2}$$

 $\textcircled{2} \rightarrow \textcircled{1}$

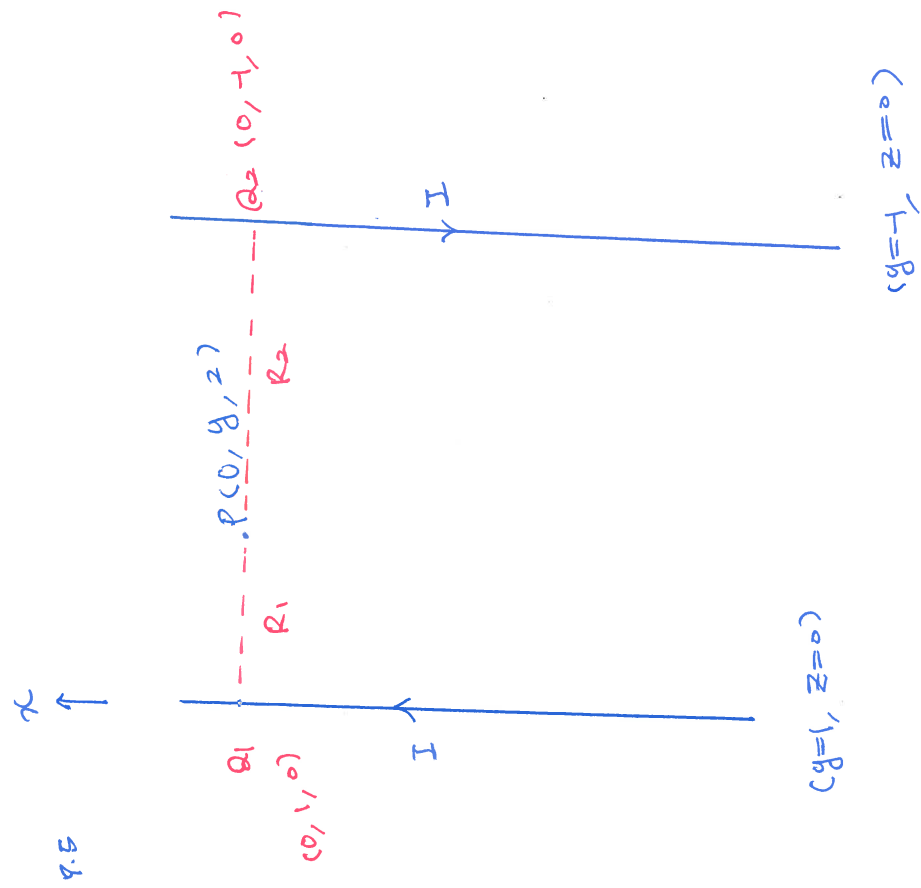
$$\begin{aligned} \vec{H} &= \frac{I}{2\pi R^2} (-\hat{x} + 3\hat{y}) = \frac{8 \times 10^{-3}}{20\pi} (-\hat{x} + 3\hat{y}) = -0.127 \times 10^{-3} \hat{x} + 0.382 \times 10^{-3} \hat{y} \quad (\text{A/m}) \\ &= -127 \hat{x} + 382 \hat{y} \quad (\mu\text{A/m}) \end{aligned}$$

c)

$$\vec{H} = \vec{H}_1 + \vec{H}_2$$

$$= -(129 + 294) \hat{x} + (196 + 382) \hat{y} \quad (\mu A/m)$$

$$= -421 \hat{x} + 578 \hat{y} \quad (\mu A/m)$$



$$I = 1 \text{ (A)}$$

$$R_1 = \sqrt{(y-1)^2 + z^2}$$

$$R_2 = \sqrt{(y+1)^2 + z^2}$$

$$\vec{H}_1 = \frac{I}{2\pi R_1} \hat{\phi}_1 \quad - (1)$$

$$\vec{H}_2 = \frac{I}{2\pi R_2} \hat{\phi}_2 \quad - (2)$$

$$\begin{aligned} \hat{\phi}_1 &= \hat{z} \times \frac{\vec{R}_1}{R_1} = \frac{1}{R_1} \hat{z} \times [(y-1)\hat{y} + z\hat{z}] \\ &= \frac{1}{R_1} [(y-1)\hat{z} - z\hat{y}] \quad - (3) \end{aligned}$$

$$\begin{aligned} \vec{H}_1 &= \frac{I}{2\pi R_1} \frac{1}{R_1} [-z\hat{y} + (y-1)\hat{z}] = \frac{I}{2\pi R_1^2} [-z\hat{y} + (y-1)\hat{z}] \quad - (4) \\ \hat{\phi}_2 &= -\hat{z} \times \frac{\vec{R}_2}{R_2} = -\frac{1}{R_2} \hat{z} \times [(y+1)\hat{y} + z\hat{z}] = -\frac{1}{R_2} [-z\hat{y} + (y+1)\hat{z}] \quad - (5) \end{aligned}$$

$$\vec{H}_2 = -\frac{I}{2\pi R_2^2} [-z\hat{y} + (y+1)\hat{z}] \quad - (6)$$

$$\vec{H} = \vec{H}_1 + \vec{H}_2$$

$$= \hat{y} \left(-\frac{I}{\pi R_1^2} + \frac{I}{\pi R_2^2} \right) + \hat{z} \left(\frac{I(y-1)}{2\pi R_1^2} - \frac{I(y+1)}{2\pi R_2^2} \right)$$

$$|\vec{H}| = \sqrt{\left(-\frac{I}{\pi R_1^2} + \frac{I}{\pi R_2^2} \right)^2 + \left(\frac{I(y-1)}{2\pi R_1^2} - \frac{I(y+1)}{2\pi R_2^2} \right)^2}$$

$$I = 1 \text{ (A)}$$

$$R_1^2 = (y-1)^2 + 4$$

$$R_2^2 = (y+1)^2 + 4$$

$$= \sqrt{\frac{I^2}{\pi^2} \left[\frac{1}{(y-1)^2 + 4} - \frac{1}{(y+1)^2 + 4} \right]^2 + \frac{I^2}{4\pi^2} \left[\frac{y-1}{(y-1)^2 + 4} - \frac{y+1}{(y+1)^2 + 4} \right]^2}$$

$$= \frac{I}{2\pi} \sqrt{4 \left[\frac{1}{y^2 - 2y + 5} - \frac{1}{y^2 + 2y + 5} \right]^2 + \left[\frac{y-1}{y^2 - 2y + 5} - \frac{y+1}{y^2 + 2y + 5} \right]^2}$$

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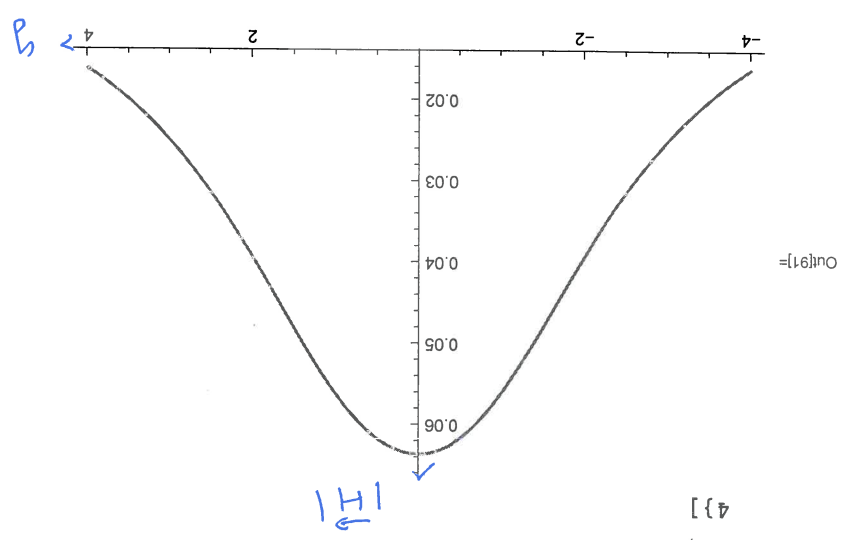
In[90]: h[X_] := (1 / (2 Pi)) Sqrt[4 (1 / (Y^2 - 2 Y + 5) - 1 / (Y^2 + 2 Y + 5))]^2 +
((Y - 1) / (Y^2 - 2 Y + 5) - (Y + 1) / (Y^2 + 2 Y + 5))^2;

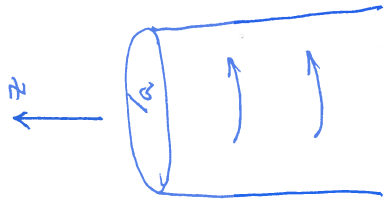
```

```

Plot[
h[X],
{X, -4, 4},
]

```





(a) $\vec{H}$ 가 ϕ 라 z 아 무관 함을 보여라

P 점의 위치를 ϕ 라 z 는 변화시켜라

물리량 상용이 변치 않으므로 $\vec{H}$ 는 ϕ 라 z 아 무관함.

(b) 다음과 같은 좌표계를 이용하여 방정식

$$r(x, y, z)$$



$$d\vec{r} = a \sin \phi \, d\phi \, d\theta \, \hat{r} + a \cos \phi \, d\phi \, d\theta \, \hat{\theta} + a \sin \phi \, d\theta \, \hat{\phi}$$

$$r = \sqrt{(x - a \cos \phi)^2 + (y - a \sin \phi)^2 + z^2}$$

$$\hat{r} = \frac{1}{r} \left[(x - a \cos \phi) \hat{x} + (y - a \sin \phi) \hat{y} + z \hat{z} \right]$$

$$d\vec{g} \times \hat{z}$$

$$= \frac{a d\phi}{r}$$

$\hat{x}$	$\hat{y}$	$\hat{z}$
$-\sin\phi$	$\cos\phi$	0
$x - a\cos\phi$	$y - a\sin\phi$	z

$$z(\cos\phi \hat{x} + \sin\phi \hat{y}) + (-x\cos\phi - y\sin\phi + a)\hat{z}$$

$$= z\hat{\rho} + (-x\cos\phi - y\sin\phi + a)\hat{z}$$

$$\Rightarrow \vec{H} = \int_c \frac{I d\vec{g} \times \hat{r}}{4\pi r^2}$$

$$= \int \frac{a d\phi}{4\pi r^3} [z\hat{\rho} + (-x\cos\phi - y\sin\phi + a)\hat{z}]$$

$$= H_\rho \hat{\rho} + H_z \hat{z}$$

$$H_\rho = \int \frac{a z}{4\pi r^3} d\phi$$

$$H_z = \int \frac{a(-x\cos\phi - y\sin\phi + a)}{4\pi r^3} d\phi$$

$$\therefore H\phi = 0$$

같은 지점이 아닌 두개의 판 사이에 P의 점은 자력 세기는 상응하라



$z \Rightarrow 2z$

$$\cdot r(x, y, z)$$



$z=0$

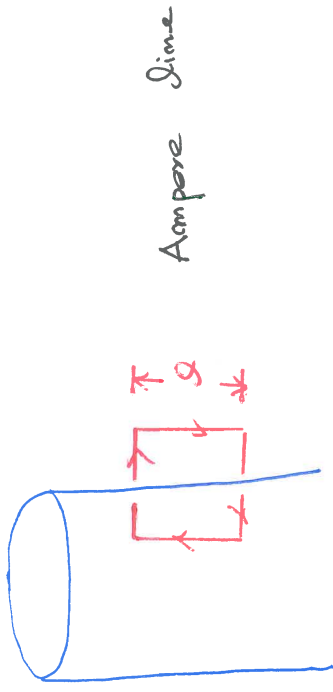
$$H_p = \int \frac{az}{4\pi r^3} d\phi + \int \frac{a(-z)}{4\pi r^3} d\phi = 0$$

Then

$$\Rightarrow H_p = 0$$

$$\Rightarrow H_p = 0, H_p = 0 \quad \Rightarrow \quad \underline{\underline{\vec{H} = H(\rho) \hat{z}}}$$

(a)



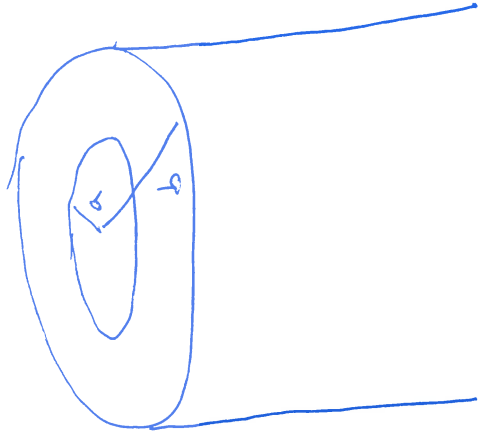
$$\oint \vec{H} \cdot d\vec{s} = I_{enc}$$

$$I_{enc} = I_{enc}$$

$$H = I_{enc}$$

$$\Rightarrow \left. \begin{array}{l} \vec{H} = I_{enc} \\ \vec{H} = I_{enc} \end{array} \right\} \begin{array}{l} \rho < a \\ \rho > a \end{array}$$

(a)



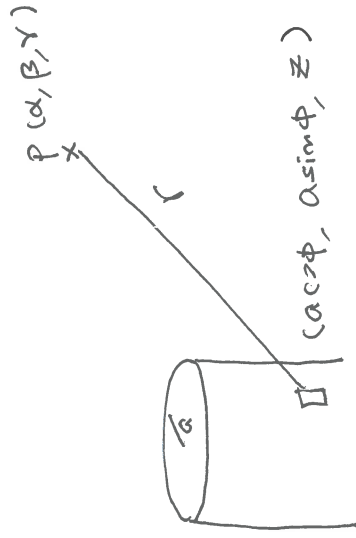
$$\rho < a \quad \vec{H} = (k_a + k_b) \hat{z}$$

$$a < \rho < b \quad \vec{H} = k_b \hat{z}$$

$$b < \rho \quad \vec{H} = 0$$

21. 例題 2.2.2. 0.2. 7. 8. 9. 10.

$$\vec{F} = \int_S \frac{\vec{F} \times \vec{r}}{4\pi r^2} dS$$



$$r = \sqrt{(a \cos \phi - \alpha)^2 + (a \sin \phi - \beta)^2 + (z - \gamma)^2}$$

$$\hat{r} = \frac{1}{r} \left[(a \cos \phi - \alpha) \hat{x} + (a \sin \phi - \beta) \hat{y} + (z - \gamma) \hat{z} \right]$$

$$\vec{F} = k_a \hat{\phi} = k_a (-\sin \phi \hat{x} + \cos \phi \hat{y})$$

* Residue Theorem !!

$$\vec{r} \times \hat{r}$$

$$= \frac{1}{r} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ -ka \sin \phi & ka \cos \phi & 0 \\ a - a \cos \phi & \beta - a \sin \phi & \gamma - z \end{vmatrix}$$

$$= \frac{1}{r} \begin{bmatrix} ka \cos \phi (\gamma - z) \hat{x} + ka (\sin \phi) (\gamma - z) \hat{y} \\ + \hat{z} [-ka \sin \phi (\beta - a \sin \phi) - ka \cos \phi (a - a \cos \phi)] \end{bmatrix}$$

$$ka (a - a \cos \phi - \beta \sin \phi)$$

$$= \frac{ka}{r} \left[(\gamma - z) \cos \phi \hat{x} + (\gamma - z) \sin \phi \hat{y} + (a - a \cos \phi - \beta \sin \phi) \hat{z} \right]$$

$$ds = a d\phi dz$$

$$\vec{H} = \int \frac{ka}{4\pi r^2} \left[(y-z) \cos\phi \hat{x} + (y-z) \sin\phi \hat{y} + (a - x \cos\phi - \beta \sin\phi) \hat{z} \right] a d\phi dz$$

$$= H_x \hat{x} + H_y \hat{y} + H_z \hat{z} \quad - \textcircled{1}$$

$$H_x = \frac{aka}{4\pi} \int \frac{(y-z) \cos\phi}{r^3} d\phi dz$$

$$H_y = \frac{aka}{4\pi} \int \frac{(y-z) \sin\phi}{r^3} d\phi dz$$

$$H_z = \frac{aka}{4\pi} \int \frac{a - x \cos\phi - \beta \sin\phi}{r^3} d\phi dz$$

} - \textcircled{2}

(i) H_x 求

$$H_x = \frac{ak_a}{4\pi} \int_{-\infty}^{\infty} dz \int_0^{2\pi} d\phi \frac{(y-z) e^{i\phi}}{[(a \cos \phi - \alpha)^2 + (a \sin \phi - \beta)^2 + (z-y)^2]^{\frac{3}{2}}}$$

$$= \frac{ak_a}{4\pi} \int_0^{2\pi} d\phi \cos \phi \int_{-\infty}^{\infty} dz \quad \text{--- (2)}$$

where

$$\int_{-\infty}^{\infty} dz = \int_{-z}^z dz \quad \left(\begin{array}{l} y \neq z \\ y \neq -z \end{array} \right)$$

$$= \int_{-\infty}^{\infty} du \frac{-u}{[(a \cos \phi - \alpha)^2 + (a \sin \phi - \beta)^2 + u^2]^{\frac{3}{2}}}$$

$$= 0 \quad (\because \text{odd function}) \quad \text{--- (4)}$$

(ii) H_y 求

$$H_y = \frac{aKa}{4\pi} \int_{-\infty}^{\infty} dz \int_0^{2\pi} d\phi \frac{(y-z) \sin \phi}{[(a \cos \phi - z)^2 + (a \sin \phi - \rho)^2 + (z-y)^2]^{\frac{3}{2}}}$$

$$= \frac{aKa}{4\pi} \int_0^{2\pi} d\phi \sin \phi \int_{-\infty}^{\infty} dz$$

$$= 0$$

(iii) H_Z π π

$$H_Z = \frac{aKa}{4\pi} \int_{-\infty}^{\infty} dz \int_0^{2\pi} d\phi \frac{a - a \cos \phi - \beta \sin \phi}{[(a \cos \phi - \alpha)^2 + (a \sin \phi - \beta)^2 + (z - \gamma)^2]^{\frac{3}{2}}}$$

— (E)

$$= \frac{aKa}{4\pi} \int_0^{2\pi} d\phi (a - a \cos \phi - \beta \sin \phi) K(\phi)$$

$$\left(\begin{array}{l} u = z - \gamma \\ du = dz \end{array} \right)$$

$$K(\phi) = \int_{-\infty}^{\infty} dz \frac{1}{[(a \cos \phi - \alpha)^2 + (a \sin \phi - \beta)^2 + (z - \gamma)^2]^{\frac{3}{2}}}$$

$$= \int_{-\infty}^{\infty} du \frac{1}{[(a \cos \phi - \alpha)^2 + (a \sin \phi - \beta)^2 + u^2]^{\frac{3}{2}}}$$

$$= 2 \int_0^{\infty} du \frac{1}{[(a \cos \phi - \alpha)^2 + (a \sin \phi - \beta)^2 + u^2]^{\frac{3}{2}}}$$

$$= 2 \int_0^{\infty} du \frac{du}{(u^2 + c^2)^{\frac{3}{2}}} \quad (c^2 = (a \cos \phi - \alpha)^2 + (a \sin \phi - \beta)^2)$$

Put

$$u = c \tan \theta$$

$$u^2 + c^2 = c^2 (1 + \tan^2 \theta) = c^2 \sec^2 \theta$$

$$du = c \sec^2 \theta \, d\theta$$

$$\Rightarrow K(\phi) = 2 \int_0^{\frac{\pi}{2}} \frac{c \sec^2 \theta}{c^3 \sec^3 \theta} \, d\theta$$

$$= \frac{2}{c^2} \int_0^{\frac{\pi}{2}} \cos \theta \, d\theta$$

$$= \frac{2}{c^2} \sin \theta \Big|_{\theta=0}^{\theta=\frac{\pi}{2}}$$

$$= \frac{2}{c^2} = \frac{2}{(a \cos \phi - d)^2 + (a \sin \phi - b)^2} \quad - \textcircled{9}$$

Q → E

$$H_z = \frac{aKa}{2\pi} \int_0^{2\pi} d\phi$$

$$\frac{a - a \cos \phi - \beta \sin \phi}{(a \cos \phi - a)^2 + (a \sin \phi - \beta)^2}$$

$$= \frac{aKa}{2\pi} \int_0^{2\pi} d\phi$$

$$\frac{a - a \cos \phi - \beta \sin \phi}{(a^2 + a^2 + \beta^2) - 2a \cos \phi - 2a\beta \sin \phi}$$

$$\left(\begin{aligned} z &= e^{i\phi} \\ dz &= i e^{i\phi} d\phi = iz d\phi \end{aligned} \right)$$

$$\frac{a - a \frac{z + z^{-1}}{2} - \beta \frac{z - z^{-1}}{2i}}{(a^2 + a^2 + \beta^2) - \cancel{2} a \frac{z + z^{-1}}{2} - \cancel{2} a \beta \frac{z - z^{-1}}{2i}}$$

$$= \frac{aKa}{2\pi} \oint_C \frac{dz}{iz}$$

$$a + \frac{z}{2}(-a + i\beta) + \frac{z^{-1}}{2}(-a - i\beta)$$

$$= \frac{aKa}{2\pi} \oint_C \frac{dz}{iz}$$

$$a - \frac{a - i\beta}{2} z - \frac{a + i\beta}{2} z^{-1}$$

$$= \frac{aKa}{2\pi} \oint_C \frac{dz}{iz}$$

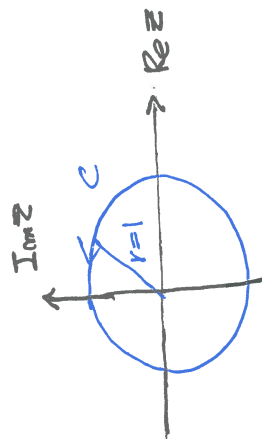
$$\frac{2a - (a - i\beta)z - (a + i\beta)z^{-1}}{(a^2 + a^2 + \beta^2) - a(a - i\beta)z - a(a + i\beta)z^{-1}}$$

$$= \frac{aKa}{4\pi} \oint_C \frac{dz}{iz}$$

$$\frac{2az - (a - i\beta)z^2 - (a + i\beta)}{(a^2 + a^2 + \beta^2)z^2 - a(a - i\beta)z - a(a + i\beta)}$$

$$= \frac{aKa}{4\pi i} \oint_C \frac{dz}{z}$$

$$\frac{z}{-a(a - i\beta)z^2 + (a^2 + a^2 + \beta^2)z - a(a + i\beta)}$$



$$= \frac{aKa}{4\pi i} \oint_C dz \frac{(\alpha - i\beta)z^2 - 2\alpha z + (\alpha + i\beta)}{z \left[\alpha(\alpha - i\beta)z^2 - (\alpha^2 + \alpha^2 + \beta^2)z + \alpha(\alpha + i\beta) \right]}$$

- ④

Pole:

$$\left(\begin{array}{l} z=0 \\ z_+ = \frac{\alpha}{\alpha - i\beta} \\ z_- = \frac{\alpha + i\beta}{\alpha} \end{array} \right)$$

- ⑤

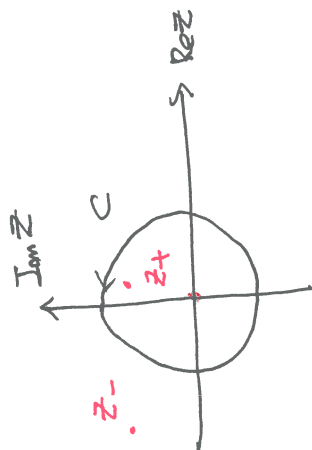
$$H_z = \frac{aKa}{4\pi i \alpha(\alpha - i\beta)} \oint_C \frac{(\alpha - i\beta)z^2 - 2\alpha z + (\alpha + i\beta)}{z(z - z_+)(z - z_-)}$$

$$= \frac{Ka}{4\pi i (\alpha - i\beta)} \oint_C dz \frac{(\alpha - i\beta)z^2 - 2\alpha z + (\alpha + i\beta)}{z(z - z_+)(z - z_-)}$$

- ⑥

$$(i) \quad \alpha^2 + \beta^2 \geq \alpha^2$$

$$|z_+| < 1, \quad |z_-| > 1$$



$$H_z = \frac{k\alpha}{2(\alpha - i\beta)} \left[\frac{\alpha + i\beta}{z_+ z_-} + \frac{(\alpha - i\beta) z_+^2 - 2\alpha z_+ + (\alpha + i\beta)}{z_+ (z_+ - z_-)} \right]$$

$$= \frac{k\alpha}{2(\alpha - i\beta)} \left[\frac{\alpha + i\beta}{z_+ z_-} + \frac{(\alpha - i\beta) \frac{\alpha^2}{(\alpha - i\beta)^2} - 2\alpha \frac{\alpha}{\alpha - i\beta} + (\alpha + i\beta)}{z_+ \left[\frac{\alpha}{\alpha - i\beta} - \frac{\alpha + i\beta}{\alpha} \right]} \right]$$

$$\left[\frac{-\alpha^2 + \alpha^2 + \beta^2}{\alpha - i\beta} \right] \quad \left[\frac{1}{(\alpha - i\beta)^2} (\alpha^2 - \alpha^2 - \beta^2) \right]$$

$$= \frac{k\alpha}{2(\alpha - i\beta)} \left[(\alpha - i\beta) - (\alpha - i\beta) \right] = 0$$

$$(ii) \alpha^2 + \beta^2 \leq a^2$$

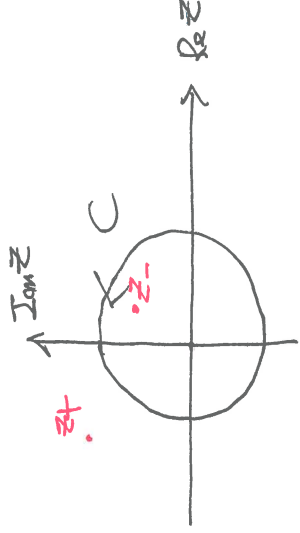
$$|z_+| > 1, \quad |z_-| < 1$$

$$H_Z = \frac{ka}{z(\alpha - i\beta)} \left[\frac{\alpha + i\beta}{z_+ z_-} + \frac{(\alpha - i\beta) z_-^2 - 2\alpha z_- + (\alpha + i\beta)}{z_- (z_- - z_+)} \right]$$

$$= \frac{ka}{z(\alpha - i\beta)} \left[\frac{\alpha + i\beta}{\frac{\alpha + i\beta}{\alpha - i\beta}} + \frac{\alpha - i\beta}{\alpha - i\beta} \right]$$

$$= \frac{ka}{z(\alpha - i\beta)} \cdot 2(\alpha - i\beta)$$

$$= ka$$



$$\frac{(\alpha - i\beta) \frac{(\alpha + i\beta)^2}{a^2} - 2\alpha \frac{\alpha + i\beta}{a} + (\alpha + i\beta)}{\frac{\alpha + i\beta}{a} \left(\frac{\alpha + i\beta}{a} - \frac{a}{\alpha - i\beta} \right)}$$

$\frac{(\alpha + i\beta)(\alpha^2 + \beta^2 - a^2)}{a^2}$
 $\frac{(\alpha + i\beta)(\alpha^2 + \beta^2 - a^2)}{a^2(\alpha - i\beta)}$

$$\alpha^2 + \beta^2 \leq \alpha^2$$

$$\alpha^2 + \beta^2 \geq \alpha^2$$

$$p < \alpha$$

$$p > \alpha$$

$$\begin{array}{c} \uparrow I \\ = \\ \} \end{array} \begin{array}{c} k\alpha \\ < \mathbb{N} \end{array} \quad 0$$

$$\begin{array}{c} \uparrow I \\ = \\ \} \end{array} \begin{array}{c} k\alpha \\ < \mathbb{N} \end{array} \quad 0$$

$\Uparrow$

$\Uparrow$

(a)

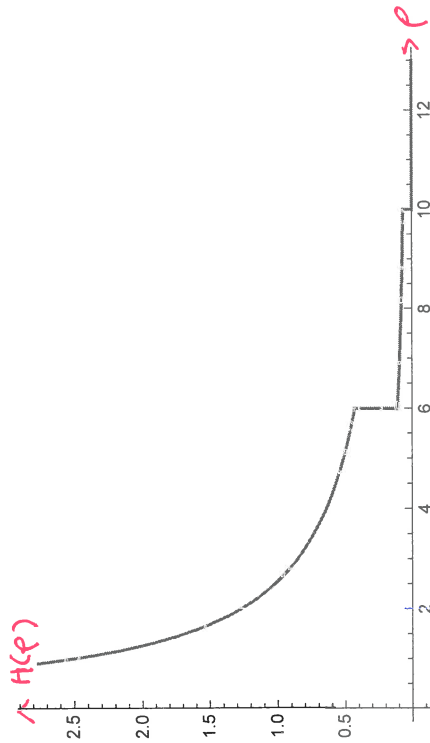
$$0 \leq \rho \leq 6 \quad H = \frac{16}{2\pi\rho} \hat{\phi} = \frac{8}{\pi\rho} \hat{\phi}$$

$$6 \leq \rho \leq 10 \quad H = \frac{4}{2\pi\rho} \hat{\phi} = \frac{2}{\pi\rho} \hat{\phi}$$

$$10 \leq \rho \quad H = 0$$

(b)

$h[x_] := \text{If}[0 \leq x \leq 6, 8 / (\text{Pi} x), \text{If}[6 < x \leq 10, 2 / (\text{Pi} x), 0]];$
 $\text{Plot}[h[x], \{x, 0, 13\}]$



(c) $\Phi_B = \int_S \vec{B} \cdot \hat{u}_n \, dS$

$$\vec{B} = \mu_0 \vec{H} = \begin{cases} \frac{\mu_0 8}{\pi \rho} \hat{\phi} & 0 \leq \rho \leq 6 \\ \frac{\mu_0 2}{\pi \rho} \hat{\phi} & 6 \leq \rho \leq 10 \\ 0 & 10 \leq \rho \end{cases}$$

$\hat{u}_n = \hat{\phi}$

$$\begin{aligned} \Rightarrow \Phi_B &= \int_0^{\pi} d\phi \int_0^6 \rho \, d\rho + \int_6^{\pi} \frac{2\mu_0}{\pi} \rho \, d\rho \\ &= \int_0^6 \frac{8\mu_0}{\pi} \rho \, d\rho + \int_6^{\pi} \frac{2\mu_0}{\pi} \rho \, d\rho \\ &= \frac{8\mu_0}{\pi} \rho^2 \Big|_0^6 + \frac{2\mu_0}{\pi} \rho^2 \Big|_6^{\pi} \\ &= \frac{2\mu_0}{\pi} \left[4\rho^2 \Big|_0^6 + \rho^2 \Big|_6^{\pi} \right] \end{aligned}$$

$$\vec{A} = (3y-z)\hat{x} + 2xz\hat{y}$$

$$(a) \vec{\nabla} \cdot \vec{A} = \frac{\partial}{\partial x}(3y-z) + \frac{\partial}{\partial y}(2xz) = 0$$

$$(b) P(2, -1, 3)$$

$$\underline{A(P) = -6\hat{x} + 12\hat{y} \quad (V/m)}$$

$$\vec{B} = \vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3y-z & 2xz & 0 \end{vmatrix} = \hat{x}(-2x) + \hat{y}(-1) + \hat{z}(2z-3)$$

$$= -2x\hat{x} - \hat{y} + (2z-3)\hat{z}$$

$$\underline{\vec{B}(P) = -4\hat{x} - \hat{y} + 3\hat{z} \quad (T)}$$

$$\underline{\vec{H}(P) = \frac{1}{\mu_0} \vec{B}(P) = \frac{1}{\mu_0} (-4\hat{x} - \hat{y} + 3\hat{z}) \quad (A/m)}$$

$$\begin{aligned} \vec{\nabla} \times \vec{H} &= \vec{J} \\ \frac{\partial}{\partial x} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ H_x & H_y & H_z \end{vmatrix} &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 0 & 0 & 0 \end{vmatrix} \\ &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 0 & 0 & 0 \end{vmatrix} \end{aligned}$$

$$\vec{\nabla} \cdot \vec{p} = 0$$

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$$\Phi_B \equiv \int_S \vec{B} \cdot \hat{u}_A \, dS$$

$$= \int_S (\vec{\nabla} \times \vec{A}) \cdot \hat{u}_A \, dS$$

$$= \int_C \vec{A} \cdot d\vec{s}$$

$$(\vec{B} = \vec{\nabla} \times \vec{A})$$

(Stokes's theorem)

$$\vec{A} = 50 \rho^2 \hat{z} \quad (\text{Wb/m})$$

$$(a) \vec{B} = \nabla \times \vec{A}$$

$$= \frac{1}{\rho} \begin{vmatrix} \hat{\rho} & \hat{\phi} & \hat{z} \\ \frac{\partial}{\partial \rho} & \frac{1}{\rho} \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ \rho^2 & 0 & 50\rho^2 \end{vmatrix}$$

$$= \frac{1}{\rho} [\rho \hat{\phi} (-100\rho)]$$

$$= -100 \rho \hat{\phi}$$

$$\vec{H} = \frac{\vec{B}}{\mu_0} = -\frac{100 \rho}{\mu_0} \hat{\phi} \quad (\text{A/m})$$

$$\vec{B} = -100 \rho \hat{\phi} \quad (T)$$

6)

$$\vec{J} = \vec{\nabla} \times \vec{H}$$

$$= \frac{1}{\rho} \begin{vmatrix} \hat{\rho} & \hat{\phi} & \hat{z} \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & (-\frac{100}{\mu_0} \hat{\phi}) & 0 \end{vmatrix}$$

$$= \frac{1}{\rho} \left[\frac{\partial}{\partial \rho} \left(-\frac{100}{\mu_0} \hat{\phi} \right) \hat{z} \right]$$

~~$$= -\frac{100}{\mu_0} \hat{z}$$~~

$$= -\frac{200}{\mu_0} \hat{z} \quad (\text{A/m}^2)$$

$$(c) \quad I = \int_S \vec{J} \cdot \hat{n} \, dS = \frac{200}{\mu_0} \cdot \pi = \frac{200 \pi}{4\pi \times 10^{-7}} = 50 \times 10^9$$

~~$$= 50 \times 10^9 \text{ A}$$~~

$$= 500 \times 10^6 \text{ (A)} = 500 \text{ (MA)}$$

$$(d) \quad \oint_C \vec{H} \cdot d\vec{l} = I_{\text{inside}} = 500 \text{ (MA)}$$